# Affective HRI: a potential impedance mismatch

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### Affective HRI . . .

"... our approach is designed to support a **rich and tightly coupled dynamic between robot and human**, where each responds contingently to the other **on an affective level**."

Cynthia Breazeal 2001.









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### Two approaches ...



Psychiatric / psychology expansive basis



Physical, chemical algorithmic reductionist basis

We'll maintain an **algorithmic**, **reductionist approach** by adopting **Dan Dennett's** conception of **algorithmic substrates** 



## Algorithmic basis for humans?

**Dan Dennett's** conception of **human beings** in terms of layered **algorithmic substrates**.

E. D. L.		Dennett's	Algorithmi	Awareness?			
From Bacteria		Progression	Substrate				
The Evolution to Bach of Minds		4. Gregorian	Nested Virtua	User Illusion (awareness/ rationality)			
		3. Popperian	Hypotheses generate & test	Hierarch- ical Bayesian Predictive coding	Feasible Automata		
DANIEL C. DENNETT		2. Skinnerian 1. Darwinian	Reinforcemer Representatio	nt learning mal learning			

Extra

Here the difference between **exhibiting** and **simulating emotion** may eventually **dissolve** if emotions are just emergent features of complex systems

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#### Dan Dennett: Awareness as an Evolved User-Illusion

Given those layers of algorithmic substrates – the personal awareness characteristic of **affect/emotions** in addition requires the **trading of reasons** within **encounters**:



the practice of sharing information in communicative actions with others, **giving and demanding reasons**, is what **creates our personal user-illusions** 

**User-illusion**: the projection on to the body of mood, emotion and affect, rather than them having an effect on the mind/brain.

#### User-Illusion ... but

... but for infants, and people such as those with dementia

'giving and demanding reasons' is infeasible.

Why not consider **affect as a co-founding constituent** rather than mere projection of user-illusions.

How to do that with minimum impact on Dennett's well-considered position?

Might each of us harbour 'proto-reasons' grounded by specific affects which duly elicit 'proto-user-illusions'?

### Grounding by affect

Here we consider **grounding** only the **most basic affect**: **touch** in the hope it may provide insights for such other affects such as pain, hunger, fear heat.

**Touch** is posited as the '**proto-reason**' that grounds awareness of a material reality comprising macroscopic solids and which simultaneously elicits the '**proto-user-illusion**' of tactile sentience.

## Algorithms, infant development

Evolutionary mechanism	Trial & Error	Natural Selection / gener	Memetic replication, Language, Thinking tools					
Dennett's Creature		Darwinian	Skinnerian		Popperian	Gregorian		
Algorithmic	Representational Learning							
substrates			Reinforcement Learning					
			sian networks					
	6			-		Nested Virtual Machines		
Infant development		CONCEPTION	Reflexive agency	DIKIH	Sensor-motor stage	Preoperational stage	Hands-on- Science	
					Onset of How about proto-reaso proto-User-Illu	f trading it: ons ision?	reasons	

### Ontological impetus

On first encountering empty space and returning into contact with external surfaces: mother's arms etc. Three factors may coalesce in an infant:

□ **instantiation** of the Bayesian **hyper-prior**, in the PC substrate, to stipulate no two solids occupy the same physical space – see A.Clarke 2013

□ 'proto-reason': grounding of explicit spatial comprehension – anchoring subsequent empirical learning from evidential chains.

□ 'proto-user-illusion': onset of contact-/tactile- sentience in the circuits that mediate the "resonant loop between body states and brain states" – e.g. those serving fingers, lips and body surfaces – providing an 'ontologically underwriting/grounding', at least while those loops are not inhibited by sleep or adaptation.

### The phenomenal present



### Impedance mismatch

Affect is no longer projected purely from the brain to body but rather exists in the "**resonant loop between body states and brain states**" with coupled **{grounding, sentience}** persisting in the loop – at least while uninhibited by sleep or adaptation.

Such a coupling would bring a qualitative aspect to a loop viewed usually as conveying purely quantitative sensory information. This qualitative aspect being 'seeded' early in life is of an ostensibly non-algorithmic nature.

This invites the prospect of an **impedance mismatch** for Affective HRI where non-algorithmic qualities get pursued on a purely algorithmic basis.

#### Affective HRI

Today this may involve **deep-learning** algorithms trained on large labeled data-sets of facial expression and gestures:

Where the expectation is that the **learnt labeling** will generalize even to those **individuals that have no capacity to label**. Here we have a duty to consider the limits of mechanistic / algorithmic explanation.

Indeed it may remain prudent when developing future robotic care-givers and nurses to ensure that any such learnt labeling continues to be **integrated into a wider context** that includes a significant human interpretive element.

### Affective HRI

... integrated into a wider context that includes a significant human interpretive element.

**Finally**, it is heartening to see such wider context being adopted in the development of a healthcare app that seeks to estimate pain on the faces of individuals with moderate-to-severe dementia

#### ePAT Pain Assessment Tool 2017



M. Atee , K. Hoti, J.D.Hughes, 2017. Psychometric Evaluation of the Electronic Pain Assessment Tool: An Innovative Instrument for Individuals with Moderate-to-Severe *Dementia*. *Dement Geriatr Cogn Disord* 44:256–267. DOI: https://doi.org/10.1159/000485377.